

Chapter 4

Transformations



4.1 - Translations

4.2 - Reflections

4.3 - Rotations

4.4 - Congruence and Transformations

4.5 - Dilations

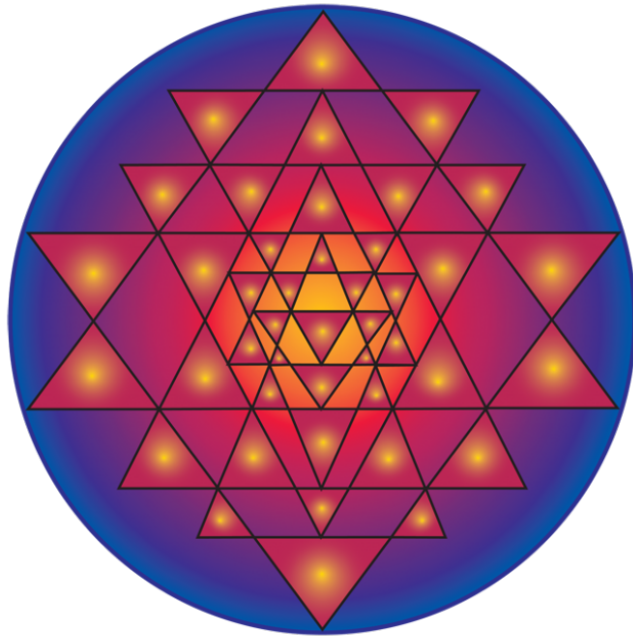
4.6 - Similarity and Transformations

4.1 - Translations

Vocabulary

Transformation

a change in the size, shape, or position of a figure



4.1 - Translations

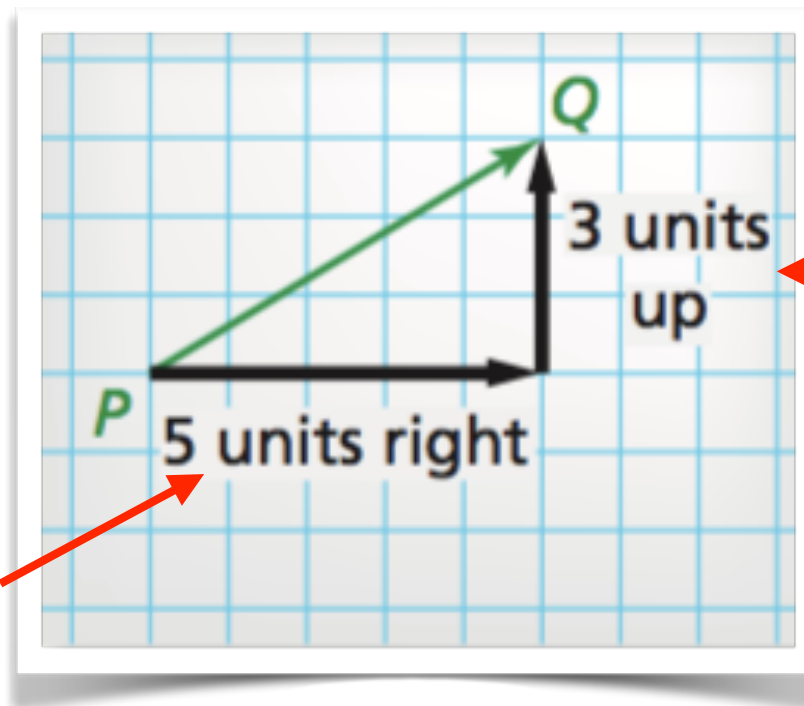
Vocabulary

Vector

a quantity that has a direction and *magnitude*, or size

“vector PQ”

or
 \overrightarrow{PQ}



Horizontal
component

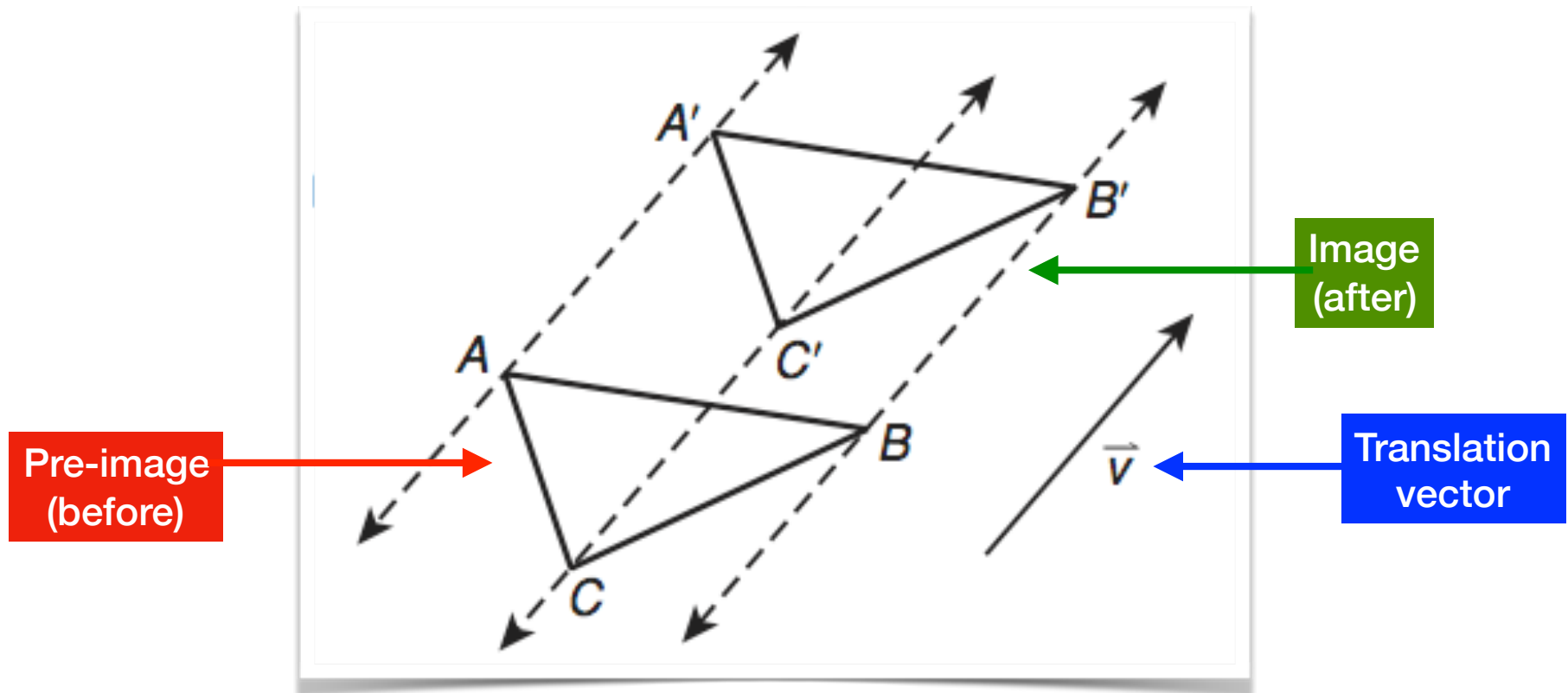
Vertical
component

Component Form = $\langle 5, 3 \rangle$

4.1 - Translations

Vocabulary

Translation	to move every point in a figure the same distance in the same direction
Isometry	a transformation that preserves length and angle measure (" <u>rigid motion</u> ")

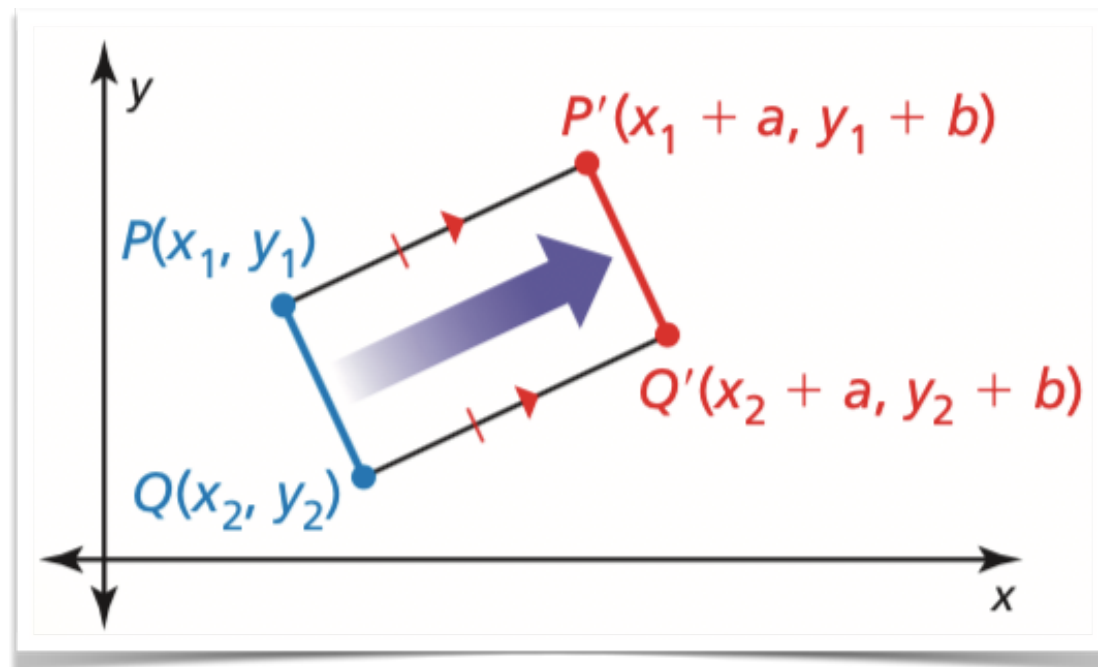


4.1 - Translations

Definition:

A translation moves every point of a figure the same distance in the same direction. More specifically, a translation maps, or moves, the points P and Q of a plane figure along a vector $\langle a, b \rangle$ to the points P' and Q' , so that one of the following statements is true.

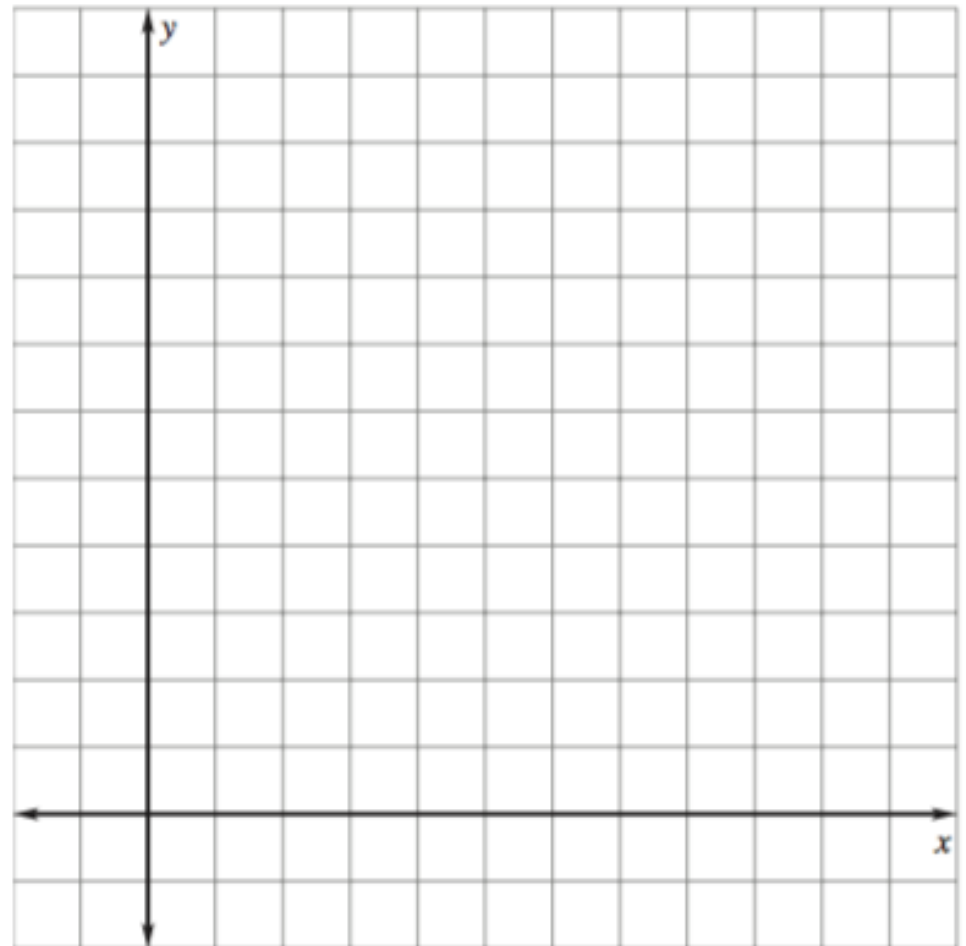
- $PP' = QQ'$ and $\overline{PP'} \parallel \overline{QQ'}$, or
- $PP' = QQ'$ and $\overline{PP'}$ and $\overline{QQ'}$ are collinear.



4.1 - Translations

Graph:

The vertices of $\triangle ABC$ are $A(0, 3)$, $B(2, 4)$, and $C(1, 0)$.
Translate $\triangle ABC$ using vector $\langle 5, -1 \rangle$.



4.1 - Translations

Translation Vector

Component Form

$$\langle a, b \rangle$$

Translation Rule

$$(x, y) \longrightarrow (x + a, y + b)$$

Convert these:

Component Form

$$\langle 4, 3 \rangle$$

$$\langle -3.2, 5.9 \rangle$$

$$\langle t - 1, 2t^2 \rangle$$

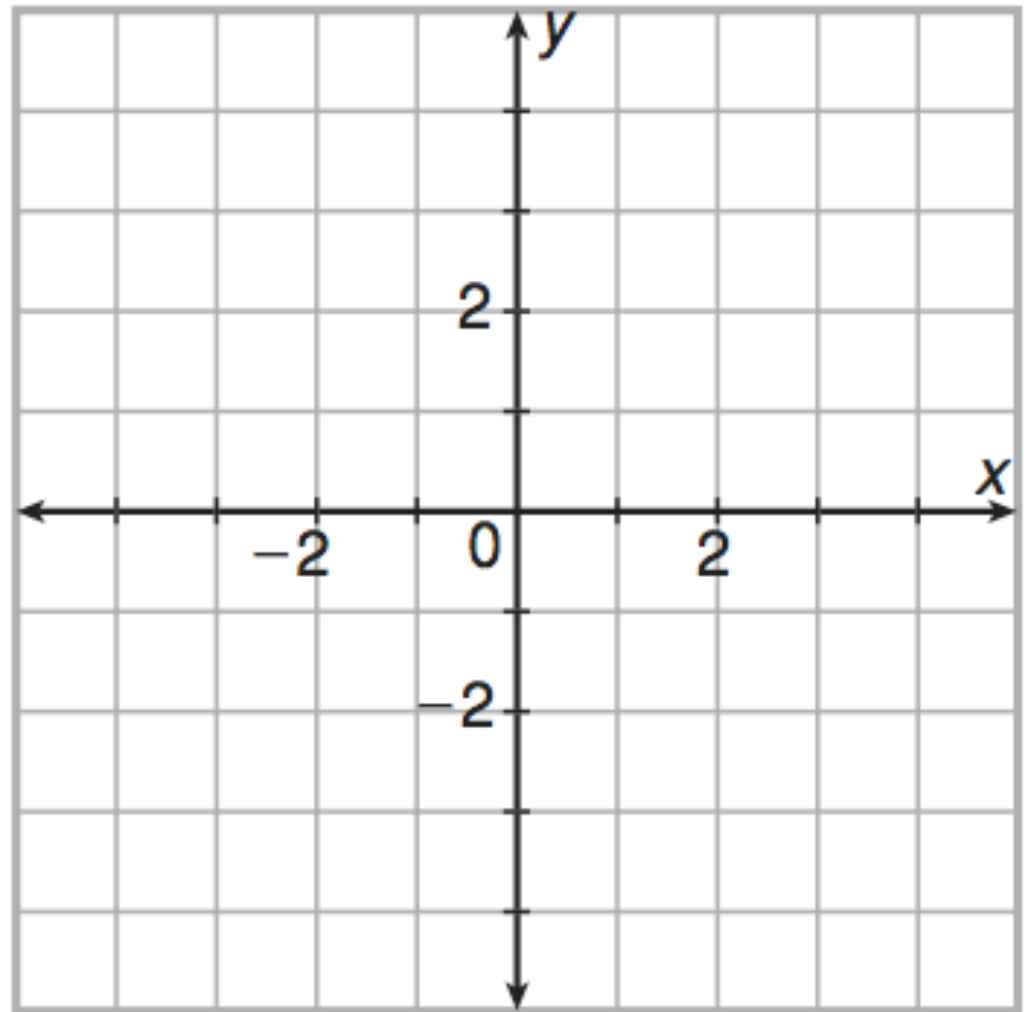
Translation Rule

4.1 - Translations

Graph:

Pre-image: $A(1, -2)$, $B(1, 0)$, $C(3, 1)$, $D(4, -3)$

Rule: $(x, y) \rightarrow (x-5, y+3)$

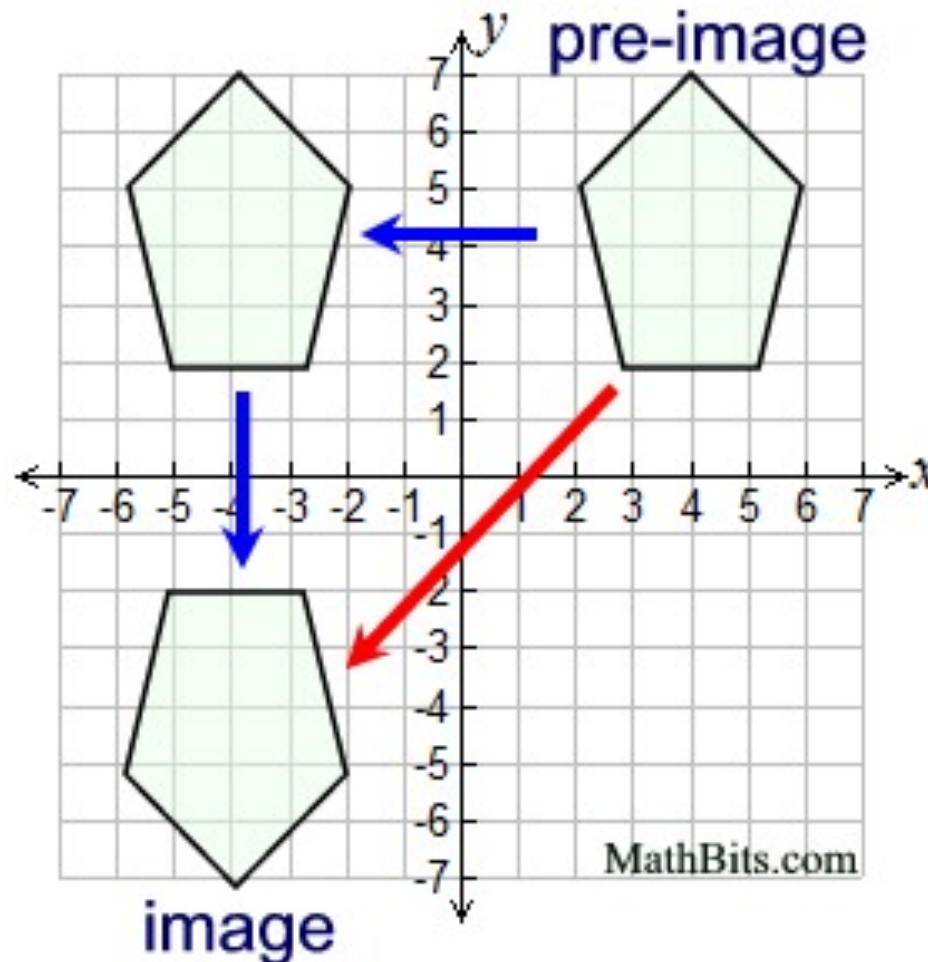


4.1 - Translations

Vocabulary

Composition of Transformations

two or more transformations are combined to form a single transformation

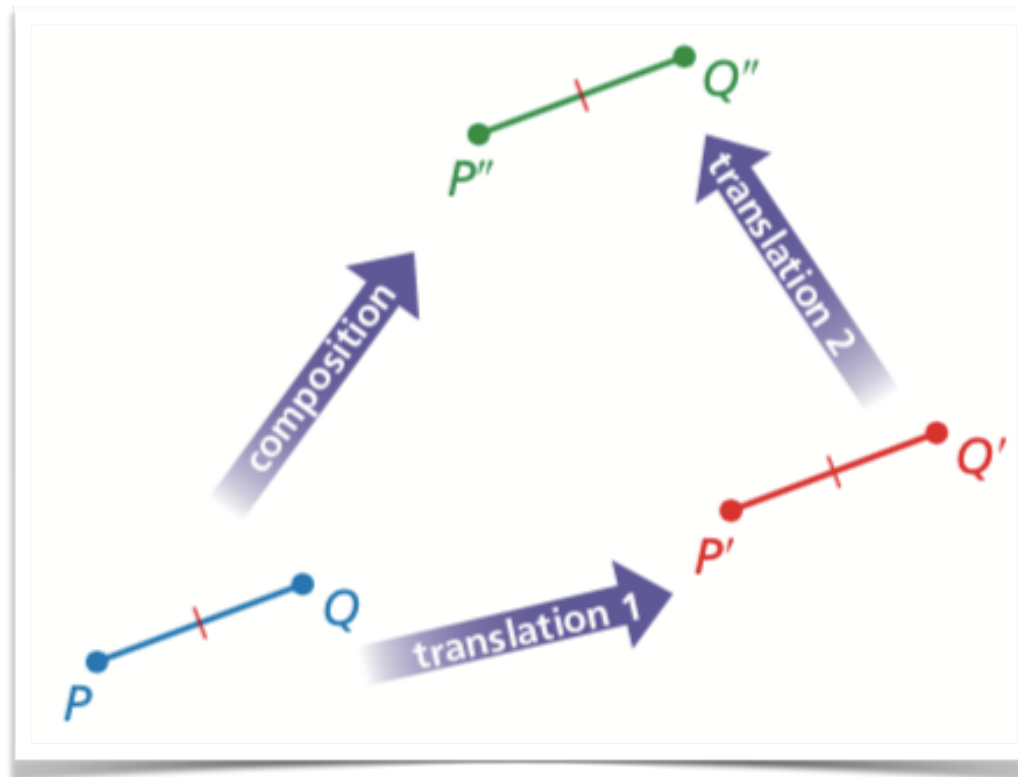


4.1 - Translations

Theorem

Composition Theorem

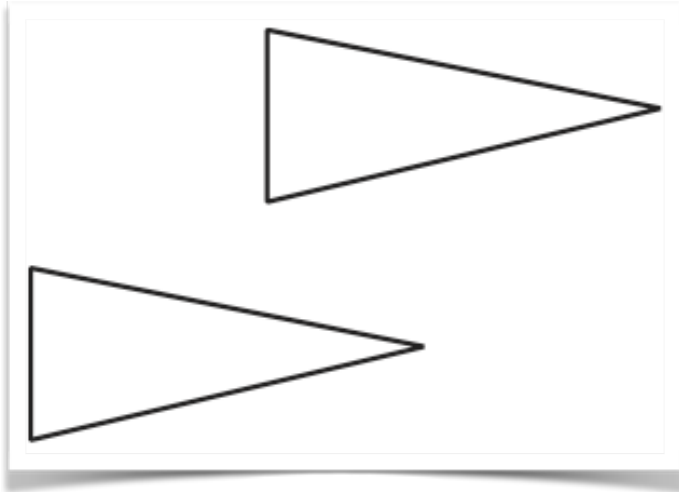
The composition of two (or more) rigid motions is a rigid motion.



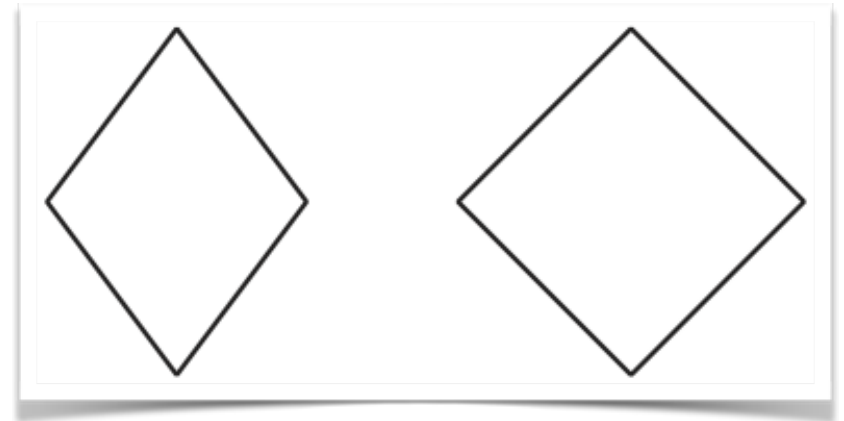
4.1 - Translations

Is this a translation?

A)



B)



C)

